

Nvidia Jetson Tk1 Development Kit User Account

Data Analytics in Medicine: Concepts, Methodologies, Tools, and Applications
Parallel Processing and Applied Mathematics
Pedestrian Detection Algorithms using Shearlets
RoboCup 2018: Robot World Cup XXII
Advances in Computational Intelligence
Hands-On GPU-Accelerated Computer Vision with OpenCV and CUDA
Euro-Par 2015: Parallel Processing Workshops
Development of a Path for the Improvement of Computational Efficiency
A Stereo Based Orb-slam Implementation for the Development of an Autonomous Robotic Walker on an Indoor Environment
Management Association, Information Resources
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advancements in data science have created opportunities to sort manage and analyze large amounts of data more effectively and efficiently applying these new technologies to the healthcare industry which has vast quantities of patient and medical data and is increasingly becoming more data reliant is crucial for refining medical practices and patient care data analytics in medicine concepts methodologies tools and applications is a vital reference source that examines practical applications of healthcare analytics for improved patient care resource allocation and medical performance as well as for diagnosing predicting and identifying at risk populations highlighting a range of topics such as data security and privacy health informatics and predictive analytics this multi volume book is ideally designed

for doctors hospital administrators nurses medical professionals it specialists computer engineers information technologists biomedical engineers data processing specialists healthcare practitioners academicians and researchers interested in current research on the connections between data analytics in the field of medicine

the two volume set Incs 10777 and 10778 constitutes revised selected papers from the 12th international conference on parallel processing and applied mathematics ppam 2017 held in lublin poland in september 2017 the 49 regular papers presented in the proceedings were selected from 98 submissions for the workshops and special sessions that were held as integral parts of the ppam 2017 conference a total of 51 papers was accepted from 75 submissions the papers were organized in topical sections named as follows part i numerical algorithms and parallel scientific computing particle methods in simulations task based paradigm of parallel computing gpu computing parallel non numerical algorithms performance evaluation of parallel algorithms and applications environments and frameworks for parallel distributed cloud computing applications of parallel computing soft computing with applications and special session on parallel matrix factorizations part ii workshop on models algorithms and methodologies for hybrid parallelism in new hpc systems workshop power and energy aspects of computations peac 2017 workshop on scheduling for parallel computing spc 2017 workshop on language based parallel programming models wlpp 2017 workshop on pgas programming minisymposium on hpc applications in physical sciences minisymposium on high performance computing interval methods workshop on complex collective systems

in this thesis we investigate the applicability of the shearlet transform for the task of pedestrian detection due to the usage of in several emerging technologies such as automated or autonomous vehicles pedestrian detection has evolved into a key topic of research in the last decade in this time period a wealth of different algorithms has been developed according to the current results on pedestrian detection benchmarks the algorithms can be divided into two categories first application of hand crafted image features and of a classifier trained on these features second methods using convolutional neural networks in which features are learned during the training phase it is studied how both of these types of procedures can be further improved by the incorporation of

shearlets a framework for image analysis which has a comprehensive theoretical basis to this end we adapt the shearlet framework according to the requirements of the practical application of pedestrian detection algorithms one main application area of pedestrian detection is located in the automotive domain in this field algorithms have to be runnable on embedded devices therefore we study the embedded realization of a pedestrian detection algorithm based on the shearlet transform

this book includes the post conference proceedings of the 22nd robocup international symposium held in montreal qc canada in june 2018 the 32 full revised papers and 11 papers from the winning teams presented were carefully reviewed and selected from 51 submissions this book highlights the approaches of champion teams from the competitions and documents the proceedings of the 22nd annual robocup international symposium due to the complex research challenges set by the robocup initiative the robocup international symposium offers a unique perspective for exploring scientific and engineering principles underlying advanced robotic and ai systems

this two volume set Incs 10305 and Incs 10306 constitutes the refereed proceedings of the 15th international work conference on artificial neural networks iwann 2019 held at gran canaria spain in june 2019 the 150 revised full papers presented in this two volume set were carefully reviewed and selected from 210 submissions the papers are organized in topical sections on machine learning in weather observation and forecasting computational intelligence methods for time series human activity recognition new and future tendencies in brain computer interface systems random weights neural networks pattern recognition deep learning and natural language processing software testing and intelligent systems data driven intelligent transportation systems deep learning models in healthcare and biomedicine deep learning beyond convolution artificial neural network for biomedical image processing machine learning in vision and robotics system identification process control and manufacturing image and signal processing soft computing mathematics for neural networks internet modeling communication and networking expert systems evolutionary and genetic algorithms advances in computational intelligence computational biology and bioinformatics

discover how cuda allows opencv to handle complex and rapidly growing image data

processing in computer and machine vision by accessing the power of gpu key features explore examples to leverage the gpu processing power with opencv and cuda enhance the performance of algorithms on embedded hardware platforms discover c and python libraries for gpu acceleration book description computer vision has been revolutionizing a wide range of industries and opencv is the most widely chosen tool for computer vision with its ability to work in multiple programming languages nowadays in computer vision there is a need to process large images in real time which is difficult to handle for opencv on its own this is where cuda comes into the picture allowing opencv to leverage powerful nvidia gpus this book provides a detailed overview of integrating opencv with cuda for practical applications to start with you ll understand gpu programming with cuda an essential aspect for computer vision developers who have never worked with gpus you ll then move on to exploring opencv acceleration with gpus and cuda by walking through some practical examples once you have got to grips with the core concepts you ll familiarize yourself with deploying opencv applications on nvidia jetson tx1 which is popular for computer vision and deep learning applications the last chapters of the book explain pycuda a python library that leverages the power of cuda and gpus for accelerations and can be used by computer vision developers who use opencv with python by the end of this book you ll have enhanced computer vision applications with the help of this book s hands on approach what you will learn understand how to access gpu device properties and capabilities from cuda programs learn how to accelerate searching and sorting algorithms detect shapes such as lines and circles in images explore object tracking and detection with algorithms process videos using different video analysis techniques in jetson tx1 access gpu device properties from the pycuda program understand how kernel execution works who this book is for this book is a go to guide for you if you are a developer working with opencv and want to learn how to process more complex image data by exploiting gpu processing a thorough understanding of computer vision concepts and programming languages such as c or python is expected

this book constitutes the thoroughly refereed post conference proceedings of 12 workshops held at the 21st international conference on parallel and distributed computing euro par 2015 in vienna austria in august 2015 the 67 revised full papers presented were carefully reviewed and selected from 121 submissions the volume includes papers from the following

workshops bigdatacloud 4th workshop on big data management in clouds euro edupar first european workshop on parallel and distributed computing education for undergraduate students hetero par 13th international workshop on algorithms models and tools for parallel computing on heterogeneous platforms lsdve third workshop on large scale distributed virtual environments omhi 4th international workshop on on chip memory hierarchies and interconnects padaps third workshop on parallel and distributed agent based simulations pelga workshop on performance engineering for large scale graph analytics reppar second international workshop on reproducibility in parallel computing resilience 8th workshop on resiliency in high performance computing in clusters clouds and grids rome third workshop on runtime and operating systems for the many core era uchpc 8th workshop on unconventional high performance computing and vhpc 10th workshop on virtualization in high performance cloud computing

this thesis proposes and evaluates the performance and accuracy of a stereo vision based simultaneous localization and mapping slam technique for calculating the position of a robotic walker on a gps denied indoor environment the mobile platform being used is a rollator equipped with ultrasonic sensors a lidar lite sensor by pulsedlight stepper motors a driver for speed control and an embedded board nvidia jetson tk1 developer kit board and a dual camera system 2x microsoft lifecam studio in a 3d printed enclosure the proposed approach made use of both cameras in the enclosure and the embedded board the goal is to aid in the navigation of the mobile platform by using affordable sensors and state of the art methods for robust localization and mapping in an indoor environment the performance of the algorithm was evaluated by comparing its processing time its accuracy and its precision as a reference marks were made every meter in a test environment for validation purposes the contributions of this research work involve the implementation in an embedded platform the online image processing through the stereo camera setup proposed and the optimization of the localization system parameters for robust accurate and fast performance of the system the images from both cameras were subject to a calibration and rectification process which will be delivered afterwards to the system by using the opencv framework resumen hoja v

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